



Feasibility Study on Higgs Pair Production in Muon Collider

Kenny Jia

May 13rd, 2021





- Signal: $\mu^+ + \mu^- \rightarrow \nu_\mu + \bar{\nu}_\mu + H + H$
- Background:
 - $\mu^+ + \mu^- \rightarrow \nu_\mu + \bar{\nu}_\mu + b + \bar{b} + Z$
 - $\mu^+ + \mu^- \rightarrow \nu_\mu + \bar{\nu}_\mu + b + \bar{b} + H$
 - $\mu^+ + \mu^- \rightarrow \nu_\mu + \bar{\nu}_\mu + b + \bar{b} + b + \bar{b}$



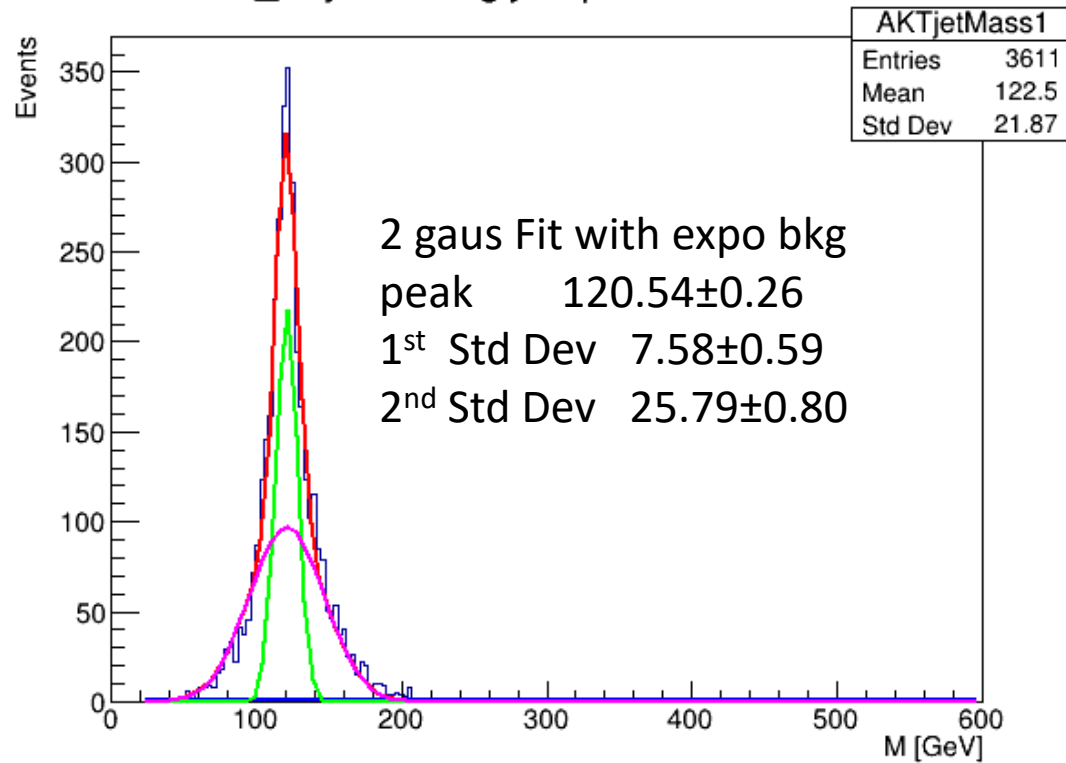
Reconstructing two Higgs bosons

- Anti- k_t Jets:
 1. Single jets pair optimize:
 - Simply leading and sub-leading jets pair, ordering by how far it is from 125GeV
 2. **Dual jets pair optimize:**
 - **Minimize the sum of the distance from jets pair to 125GeV**

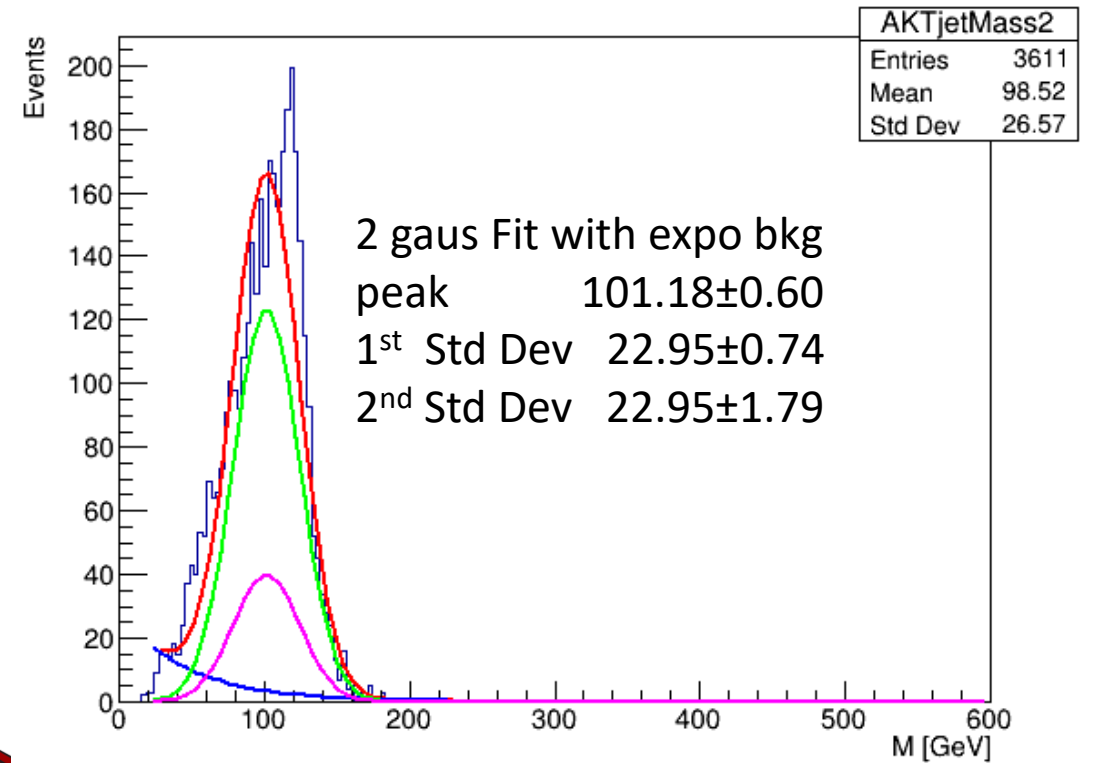


Anti- k_t jet for 10k events ($n_{\text{Jets}} \geq 4$)

Anti_KTjet leading jets pair invariant mass

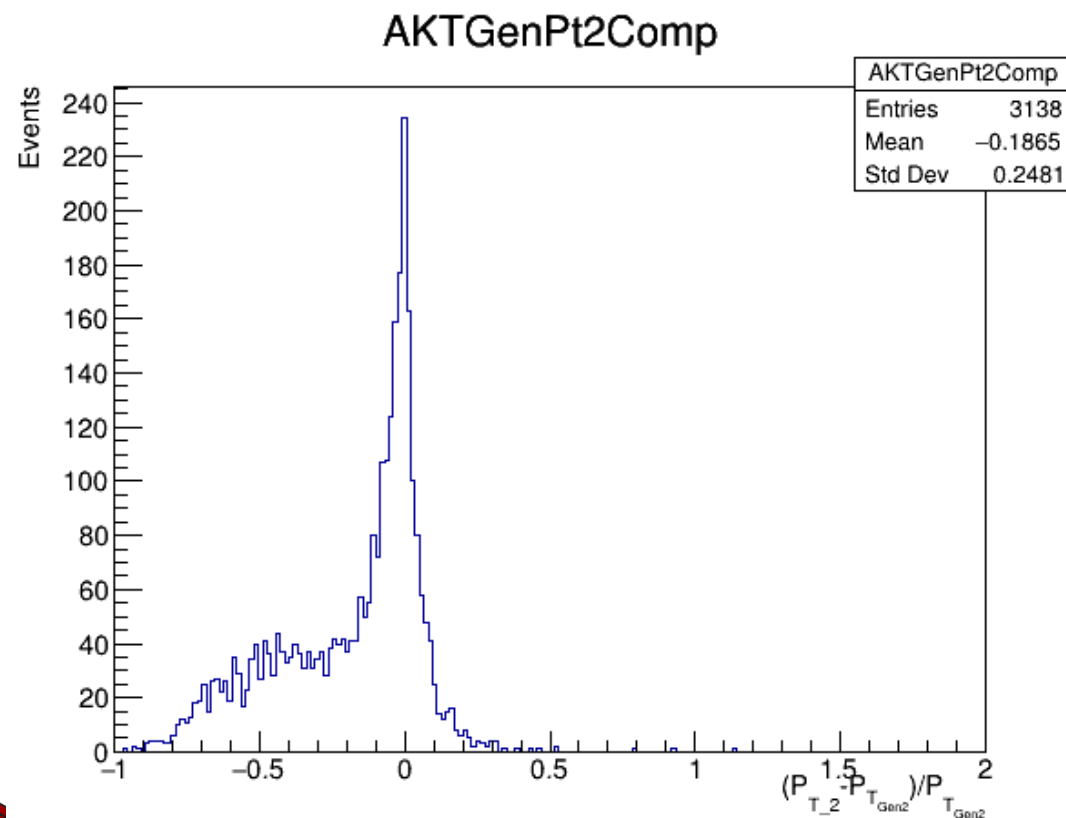
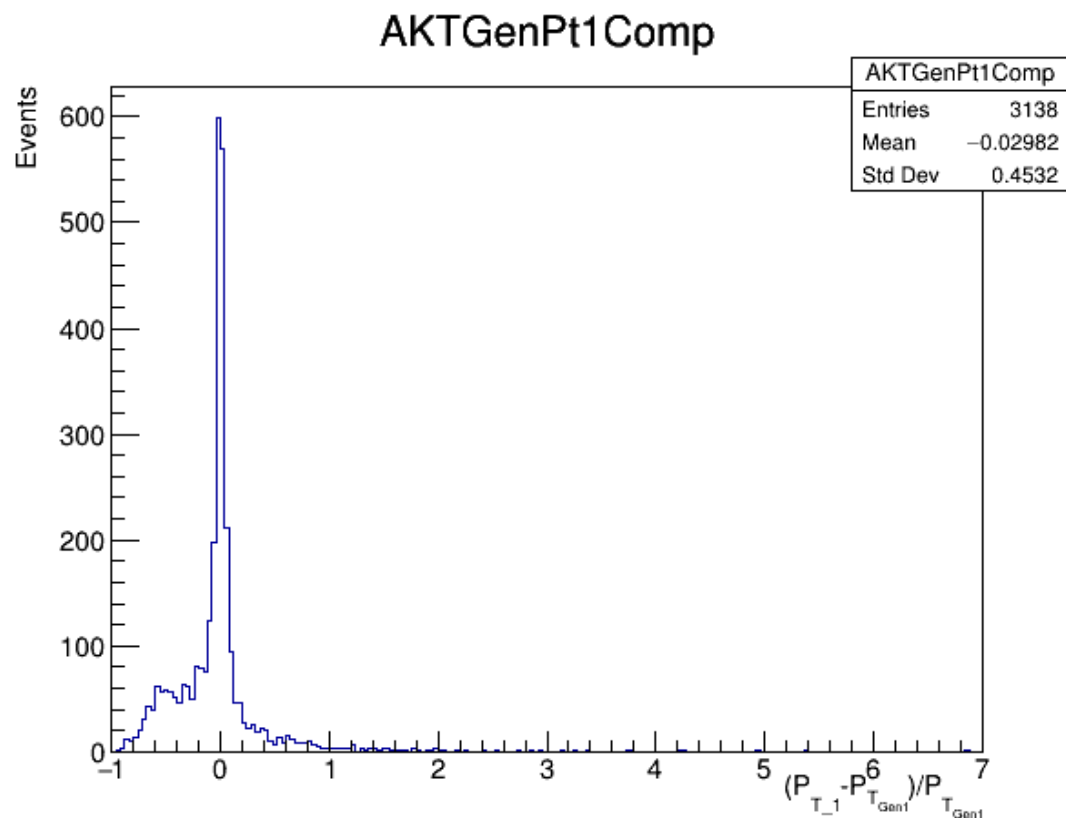


Anti_KTjet sub-leading jets pair invariant mass



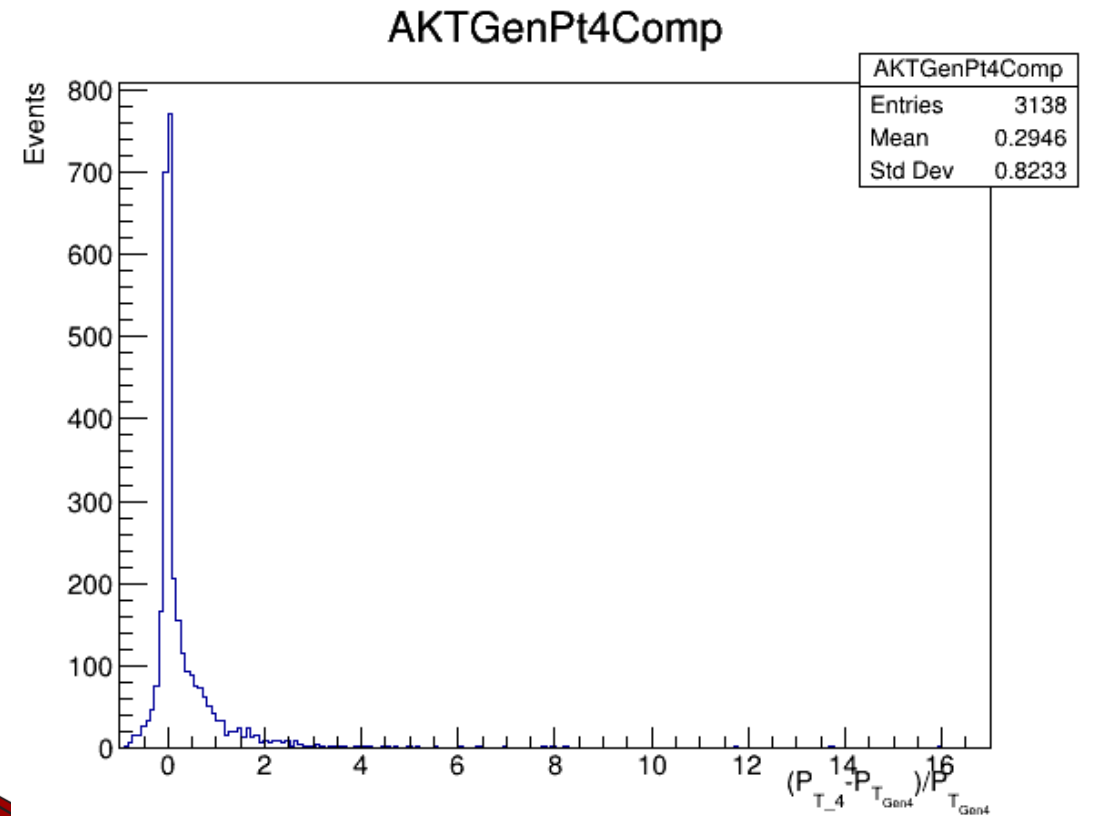
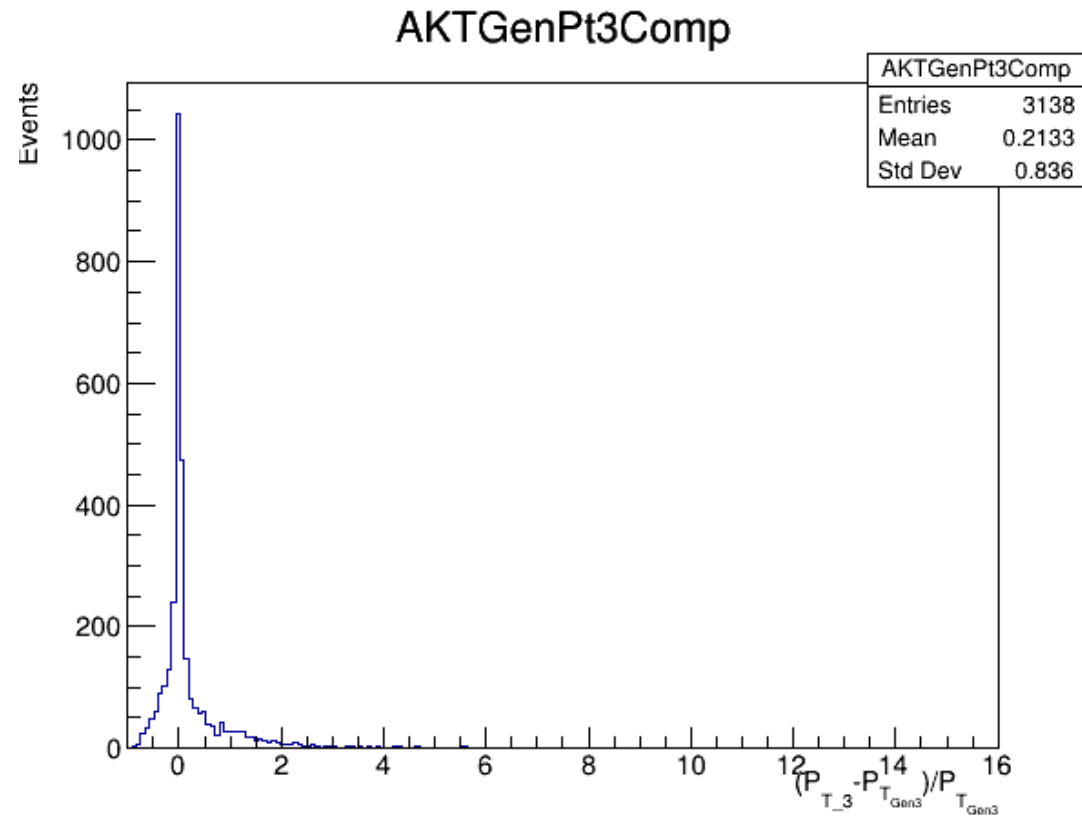


Resolution of the first jets pair



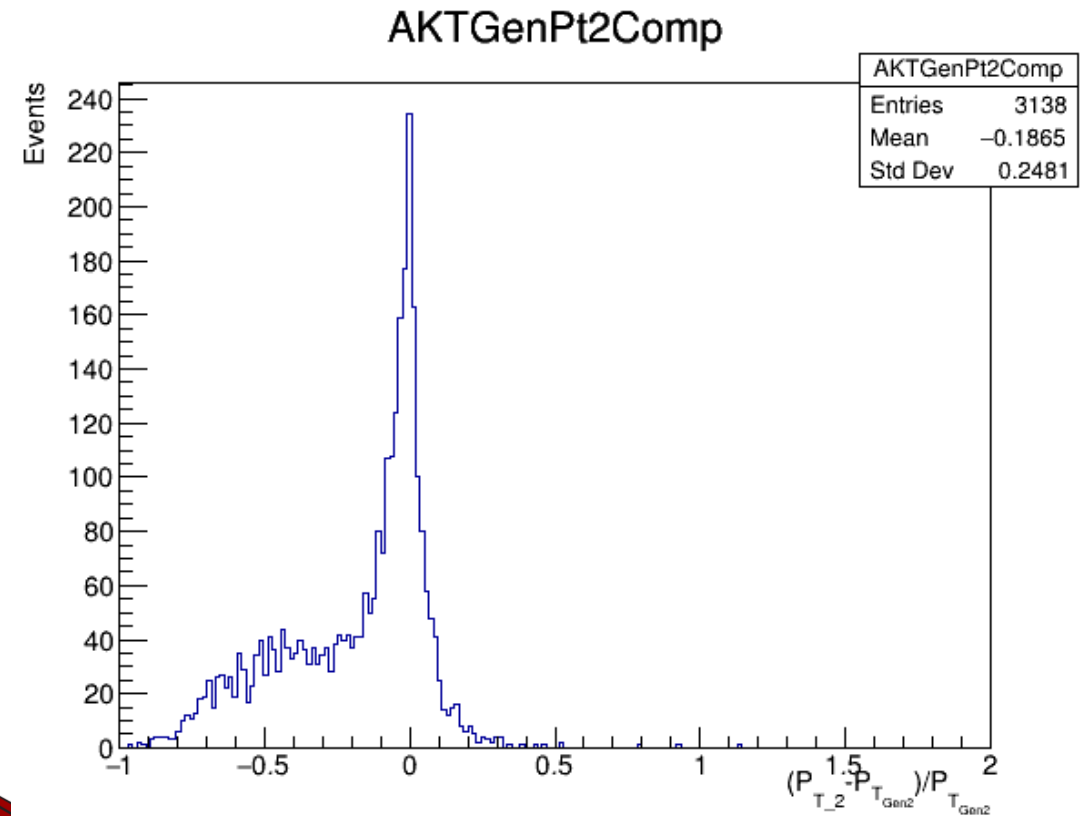
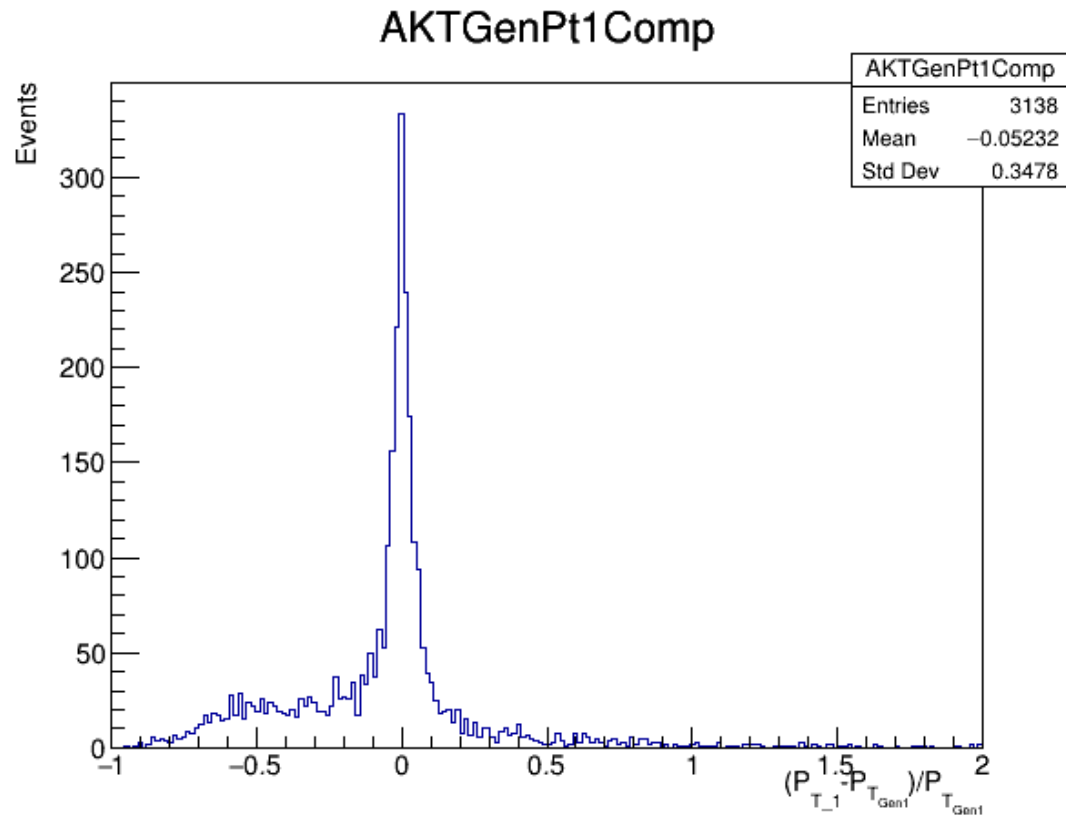


Resolution of the second jets pair



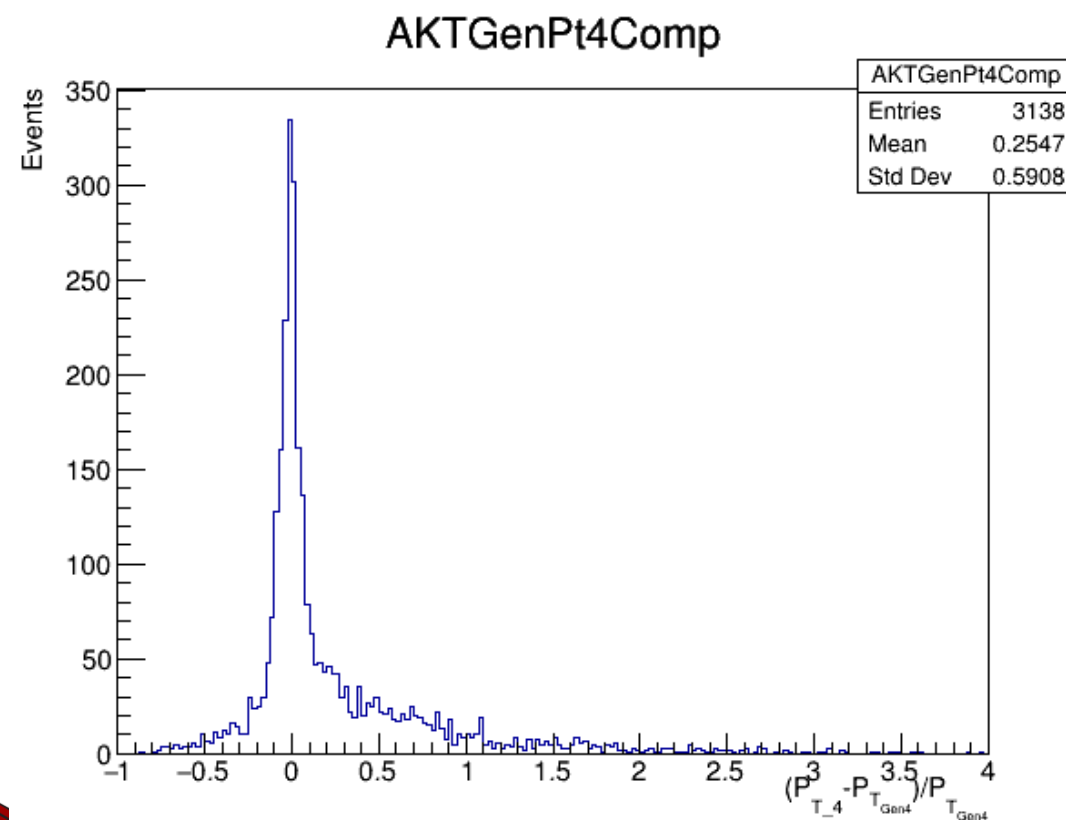
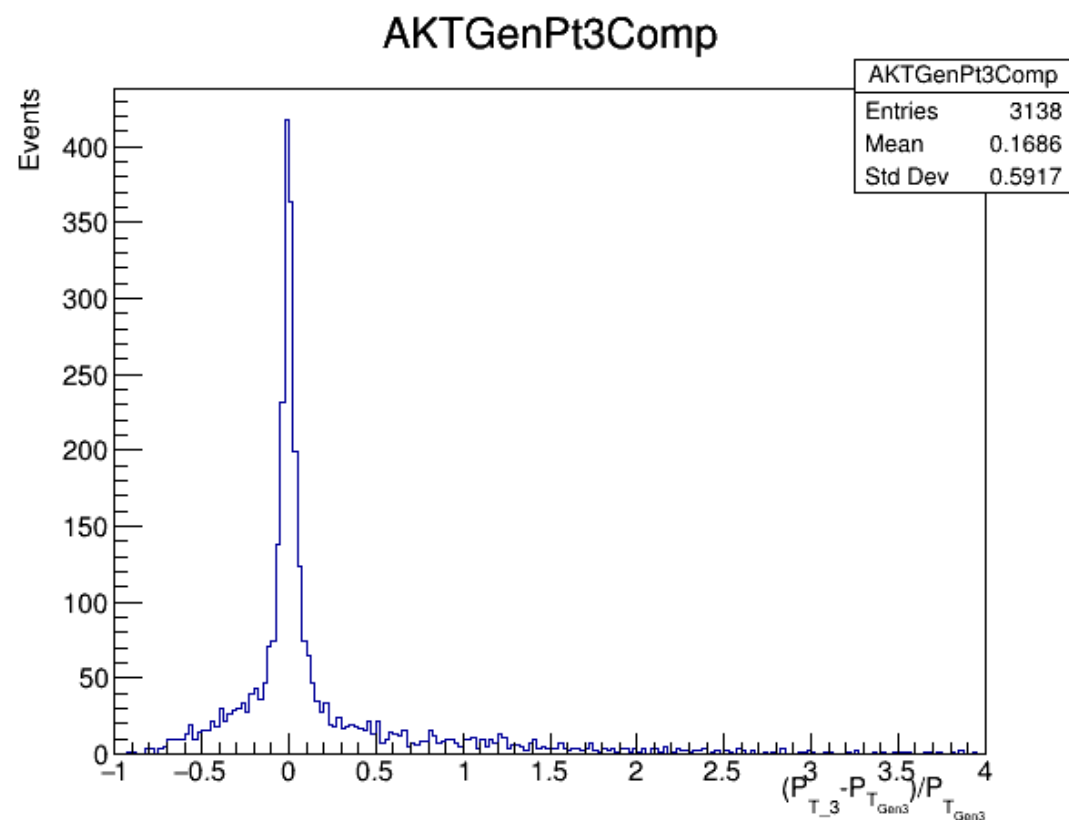


Zoom in of first pair resolution





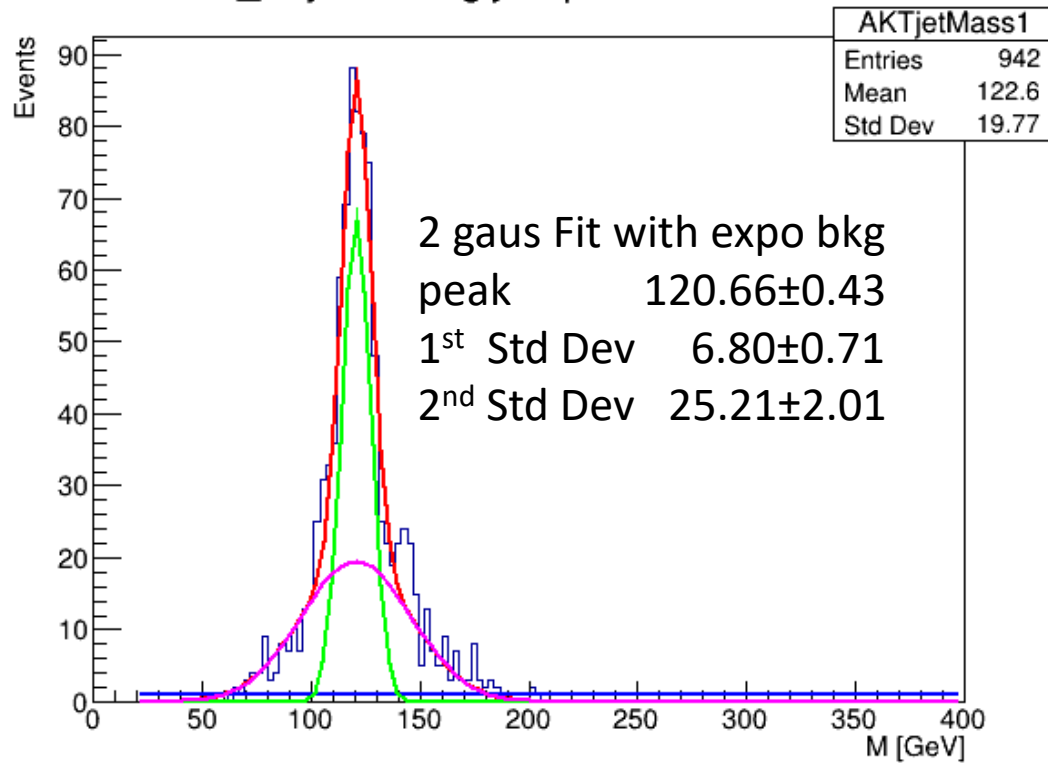
Zoom in of second pair resolution



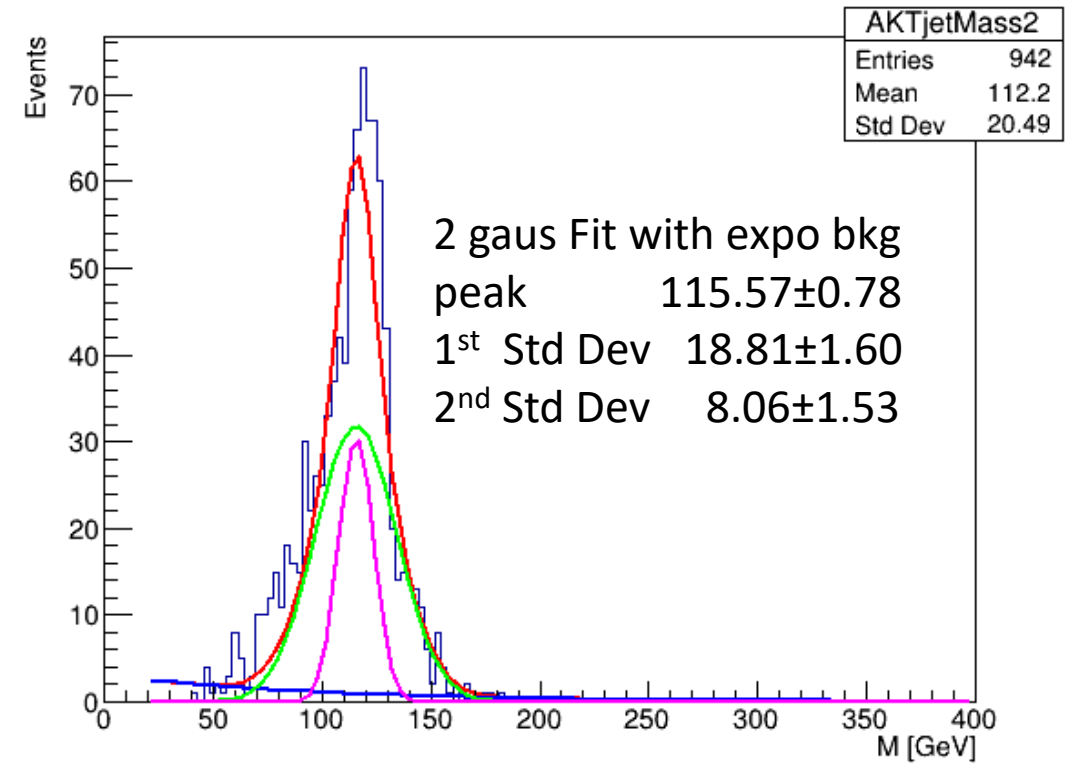


Try cut of poorly-constructed jets ($\sigma_{P_T} \geq 10\%$)?

Anti_KTjet leading jets pair invariant mass



Anti_KTjet sub-leading jets pair invariant mass





Appendix: data card for run anti- k_t jet algo

```
1633 #####
1634 # Jet finder AKT
1635 #####
1636
1637 module FastJetFinder FastJetFinderAKt {
1638     # set InputArray Calorimeter/towers
1639     set InputArray EFlowMerger/eflow
1640
1641     set OutputArray AKTjets
1642
1643     # algorithm: 1 CDFJetClu, 2 MidPoint, 3 SIScone, 4 kt, 5 Cambridge/Aachen, 6 antikt
1644     set JetAlgorithm 6
1645     set ParameterR 0.5
1646
1647     set JetPTMin 20.0
1648 }
```



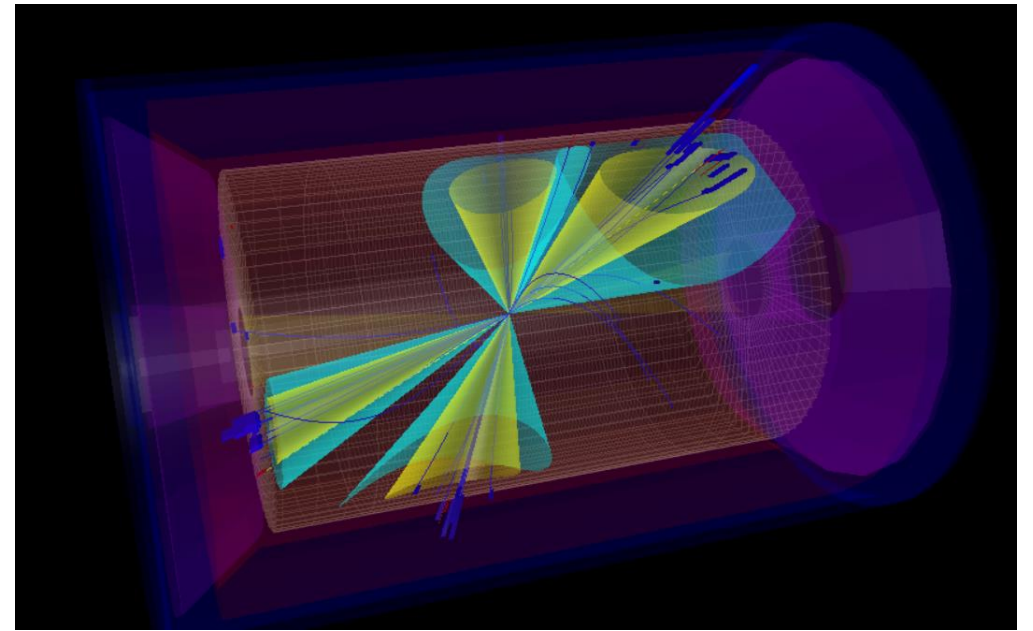
Appendix: Dual jets pair optimize

- Anti- k_t Jets:
 1. Arbitrarily pick two from all jets
 2. Choosing one pair that is closest to 125GeV from the rest to be the respective sub-leading jets pair.
 3. Stored all info in a 2d array. Finally choosing the choice with smallest sum of distance from 125GeV



Appendix: For exactly for 4 jets in one event

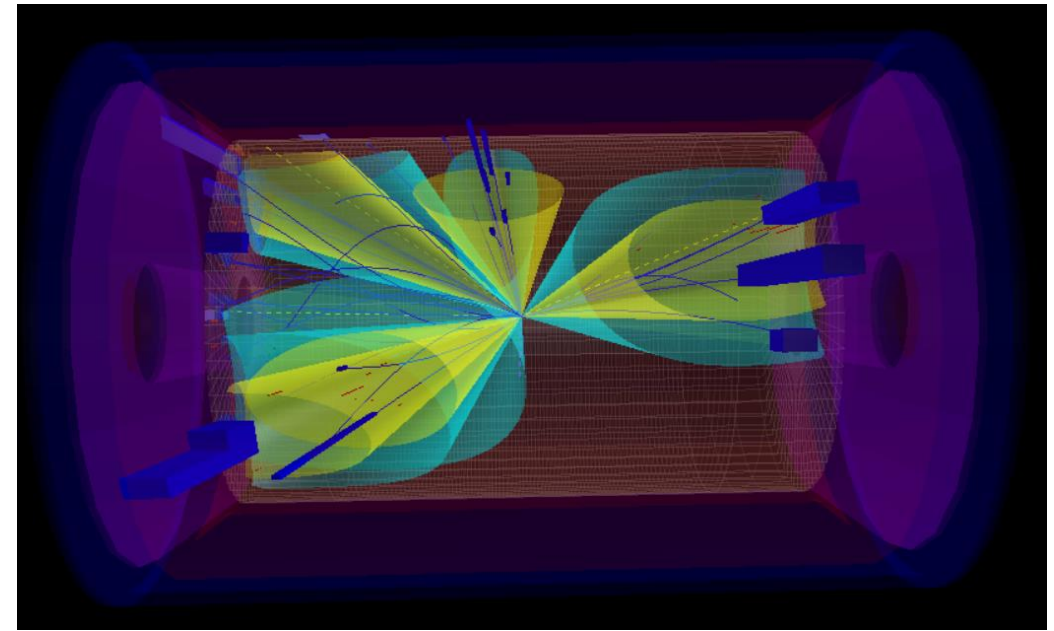
1. C_2^4 different choices for picking the “leading” jets pair, then the remain two just forms the “sub-leading” jets pair.
2. Store the invariant masses and entry info into a 2d array AKTjetspair[C_2^4] [6].
3. Final decision is the one that minimize the sum of the distance from 125GeV





Appendix: For at least 4 jets ($n_{\text{Jet}} = n$) in one event

1. C_2^n choices for the “leading” jets pair.
2. Loop through remain C_2^{n-2} choice for “sub-leading” jets pair choosing the one which closest to 125GeV
3. Store the invariant masses and entry info into a 2d array `AKTjetpair[C_2^n]` [6].
4. Final decision is the one that minimize the sum of the distance from 125GeV





Appendix: Double gaussian fit with exponential background

- Fit to curve:

- $f(x) = A_1 \exp[-\frac{1}{2}(\frac{x-\mu_1}{\sigma_1})^2] + A_2 \exp[-\frac{1}{2}(\frac{x-\mu_2}{\sigma_2})^2] + \exp(A_3 - \lambda x)$
- Tight bound on almost all parameters

```
TF1 *jetpair1fit = new TF1("jetpair1fit", "gaus+gaus(3)",25,600);
TF1 *jetpair2fit = new TF1("jetpair2fit", "gaus+gaus(3)+expo(6)",25,600);
TF1 *fSignal = new TF1("fSignal","gaus+gaus(3)",20,600);
TF1 *fBackground = new TF1("fBackground","expo", 20,600);
Double_t param[8];
```

```
jetpair2fit->SetParameters(200,133,10,20,100,10,2,-0.0001);
jetpair2fit->SetParLimits(0,80,200);
jetpair2fit->SetParLimits(1,110,130);
jetpair2fit->SetParLimits(2,5,25);
jetpair2fit->SetParLimits(6,0,8);
jetpair2fit->SetParLimits(7,-1,-0.0001);
jetpair2fit->SetParLimits(4,50,109);
jetpair2fit->SetParLimits(5,5,30);
```

```
jetpair1fit->SetParameters(300,120,10,40,125,10,2,-0.0001);
jetpair1fit->SetParLimits(0,100,400);
jetpair1fit->SetParLimits(1,110,120);
jetpair1fit->SetParLimits(2,5,30);
/*jetpair1fit->SetParLimits(6,0,8);
jetpair1fit->SetParLimits(7,-1.5,-0.0001);*/
jetpair1fit->SetParLimits(4,120,140);
jetpair1fit->SetParLimits(5,5,40);
```




Kinematic fitting

