



Implementation of NRAO's imaging workflow in HTCondor

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Astronomy
Observatory

Abstract

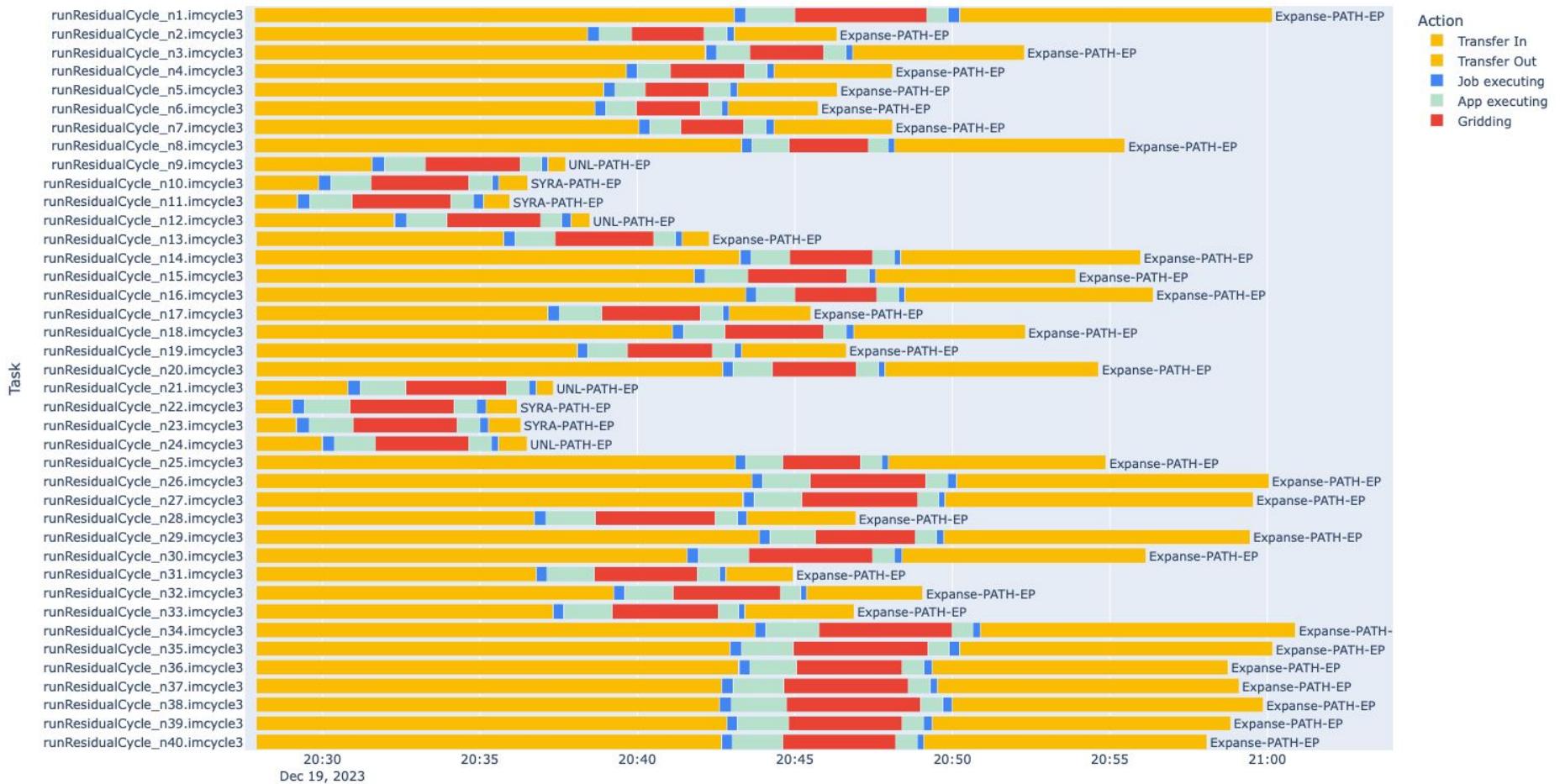
A distributed workflow to make interferometric images was developed at NRAO and successfully deployed to nearly one hundred GPUs gathering resources from PATH and OSPool, to enable processing VLA data to make the deepest radio image of the Hubble Ultra Deep Field. We present the details of the HTCondor implementation of this workflow, as well as detailed results of performance metrics and how these results helped in identifying and prioritizing work on improvement opportunities.

Some facts about December's imaging run

- Deepest radio image of the Hubble Ultra Deep Field
- 76 concurrent GPU jobs (peak)
- 2.7 jobs/minute, 1.5 TB/h (average of fastest cycle)
- ~ 750 total GPU hours
- 1650 jobs
- 5 days wall clock time, ~ 24 hours aggregate processing time



Concurrency plot



Analysis of the concurrency plots helps identifying and prioritizing improvement opportunities

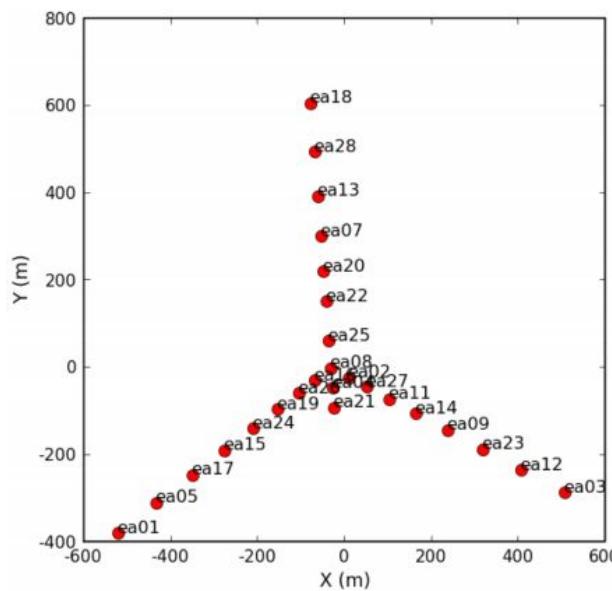
Future work / challenges from my talk on HTC23 (prioritized tasks completed/ongoing marked red)

- Improve IO efficiency of gridding jobs
- Further expand data partitioning to other axes
- Integrate/test new model cycle software module
- “Gather barrier”
 - Optimize DAG design to minimize barrier
 - Investigate scalable design solutions
- Scale up residual cycle partitioning / distribution by at least 1-2 orders of magnitude - will need larger number of available GPUs, or hybrid distribution model (GPU/CPU)

From the infrastructure's perspective, the concurrency plot can be a powerful tool to help identify sites or EPs with long transfer times, especially if combined with unit tests designed to monitor system performance.

Interferometric Imaging is a Computational Problem

Antenna positions (VLA)

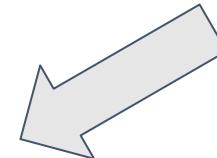


Dirty Image

Distance, Orientation of all antenna pairs



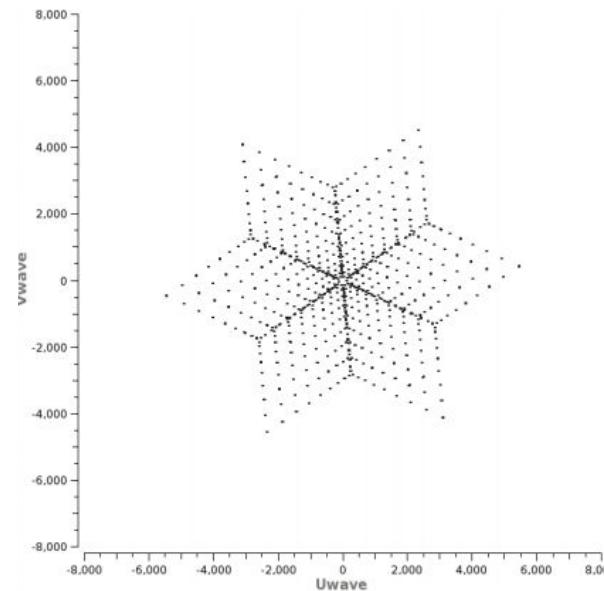
Gridding + FFT⁻¹ of measurements



Post processing

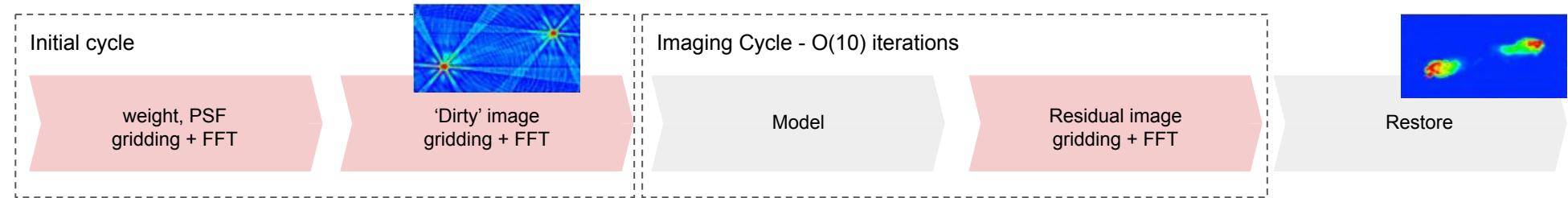


Sampling function



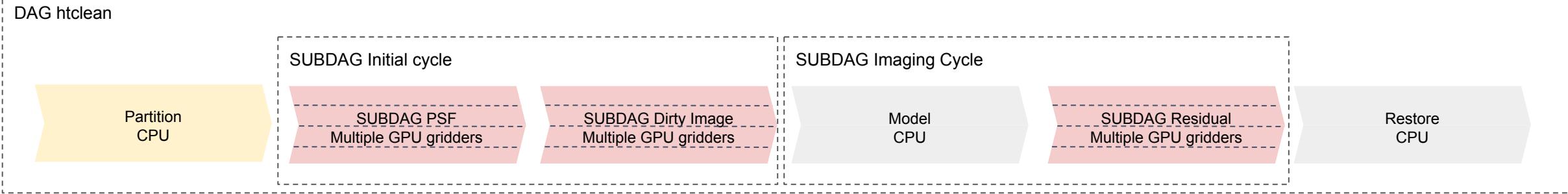
Final Image

Interferometric imaging workflow (CLEAN method)



- Initial cycle
 - compute individual data weights and point spread function (PSF) for image reconstruction
 - compute 'dirty' image
- Imaging cycle - typically $O(10)$ iterations
 - update Model: iteratively 'deconvolve' sampling function (PSF) and identify model components
 - update Residual: subtract model components from data and make new image
- Restore: combine PSF, model and residual to generate final image

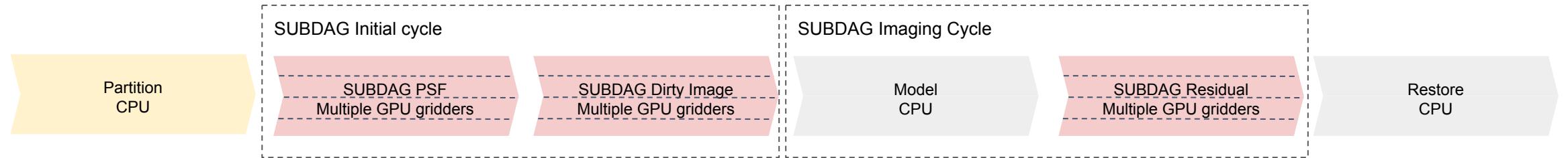
HTClean implementation (HTCondor + CLEAN = HTClean)



- early dev. 2020 (multiple CPU jobs) → 1st GPU job 2021 → multiple GPUs 2022 → deployment/development on PAth: late 2022 → Science run Dec 2023
- Nested DAGs with a RETRY+POSTSCRIPT to control iterations
- HTClean breaks down the imaging process in independent sessions that can be distributed
 - Addresses asymmetry in the two main stages of imaging:
 - residual cycle: highly parallelizable, high FLOPS, visibility domain
 - model cycle: serial (*continuum* imaging), low FLOPS, image domain

HTClean implementation - main DAG

DAG htclean



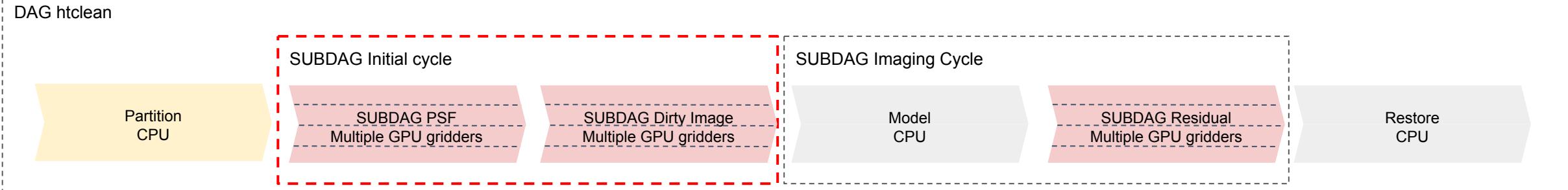
```
JOB           MSpartition      MSpartition.htc
SUBDAG EXTERNAL initialCycle    initialCycle.dag
SUBDAG EXTERNAL imagingCycle   imagingCycle.dag
JOB           makeFinalImages  makeFinalImages.htc

SCRIPT PRE    initialCycle     set_retry.sh -1
SCRIPT PRE    imagingCycle    set_retry.sh $RETRY
RETRY         imagingCycle    8
SCRIPT POST   imagingCycle    stopIterations.sh

PARENT        MSpartition      CHILD          initialCycle
PARENT        initialCycle     CHILD          imagingCycle
PARENT        imagingCycle    CHILD          makeFinalImages

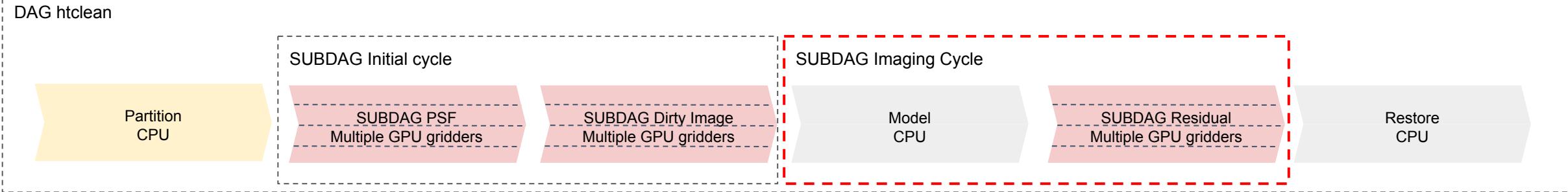
VARS          ALL_NODES        jobmode=$(JOB)
VARS          ALL_NODES        input_file="../bin/libra_htclean.def"
VARS          ALL_NODES        partId="n"
```

HTClean implementation - SUBDAG initial cycle



SUBDAG EXTERNAL	makePSF	makePSF.dag
JOB	gatherPSF	gatherPSF.htc
SUBDAG EXTERNAL	makeDirtyImage	makeDirtyImage.dag
JOB	gather	gather.htc
SCRIPT PRE	makePSF	writeGriddingDAGs.sh libra_htclean.def
SCRIPT PRE	gatherPSF	makeInputFileList.sh libra_htclean.def imcycle.htc psf
SCRIPT PRE	gather	makeInputFileList.sh libra_htclean.def imcycle.htc dirty
VARS	ALL_NODES	jobmode="\$(JOB)"
VARS	ALL_NODES	input_file="..../bin/libra_htclean.def"
VARS	ALL_NODES	partId="n"
PARENT	makePSF	CHILD gatherPSF
PARENT	makePSF	CHILD makeDirtyImage
PARENT	makeDirtyImage	CHILD gather
PARENT	gatherPSF	CHILD gather

HTClean implementation - SUBDAG imaging cycle



```
JOB          runModelCycle    runModelCycle.htc
SUBDAG EXTERNAL runResidualCycle runResidualCycle.dag
JOB          gather           gather.htc

SCRIPT PRE   gather          makeInputFileList.sh libra_htclean.def imcycle.htc residual

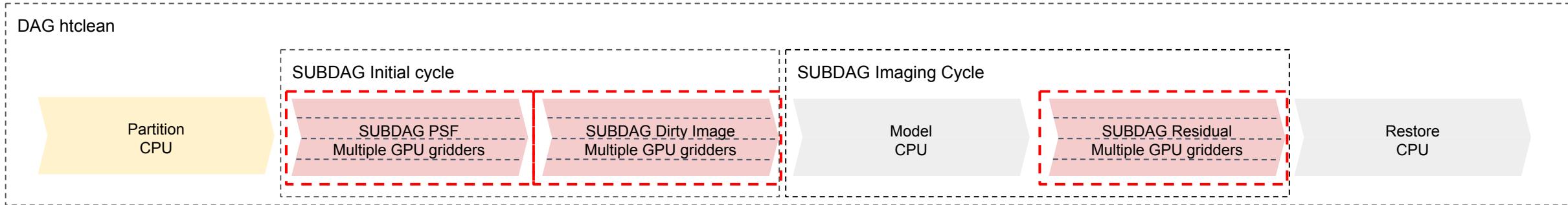
VARS          ALL_NODES       jobmode="$(JOB)"
VARS          ALL_NODES       input_file="../bin/libra_htclean.def"
VARS          ALL_NODES       partId="n"

RETRY         runModelCycle   2

PARENT        runModelCycle   CHILD runResidualCycle
PARENT        runResidualCycle CHILD gather
```

HTClean implementation - Inner DAGs

DAG htclean



- Inner DAGs are written dynamically according to input parameters

from initialCycle.dag:

SCRIPT PRE

makePSF

writeGriddingDAGs.sh libra_htclean.def

```
for i in `seq 1 ${nparts}`
do
    JOBtext+="JOB      ${DAG}_n${i}      ${DAG}.htc"${'\n'}
    VARStext+="VARS      ${DAG}_n${i}      partId=\\"n${i}\\"${'\n'}
    cfsiz=`du -sh ${cfcachedir}/${cfcache}.tar | awk '{gsub(/G/, "", $1)}{print int($1)+1}'`
    mssiz=`du -sh ${msdir}/${msname}_n${i}.ms.tar | awk '{gsub(/G/, "", $1)}{print int($1)+1}'`
    diskrq=$((2 * (cfsiz + mssiz) + 10))
    VARStext+="VARS      ${DAG}_n${i}      diskResidual=\\"${diskrq} G\\"${'\n'}
done
VARStext+="VARS      ALL_NODES      jobmode=\\"${jobmode}\\"${'\n'}
VARStext+="VARS      ALL_NODES      input_file=\\"..//bin/${input_file}\\"${'\n'}
VARStext+="RETRY     ALL_NODES      2"
TEXT=${JOBtext}${'\n'}${'\n'}${VARStext}
echo "${TEXT}" > ${DAG}.dag
```

Dynamic disk allocation

Other highlights of the current implementation

Data transfers:

- auto-expand input data tarballs

```
transfer_input_files = $(cfcachedir)$(cfcache).tar?pack=auto,  
$(msdir)/$(msname)_$(partId).ms.tar?pack=auto,  
$(imagesdir)/$(imagename).divmodel.imcycle$(imcycle).tar?pack=auto
```

Job configuration:

- detailed GPU requirements

```
+DESIRED_GPU_MIN_Capability = 8.0  
+DESIRED_GPU_MIN_GlobalMemoryMb = 24000  
+DESIRED_GPU_MIN_DriverVersion = 12.0  
RequireGPUs = (Capability >= DESIRED_GPU_MIN_Capability) && (GlobalMemoryMb >  
DESIRED_GPU_MIN_GlobalMemoryMb) && (DriverVersion >= DESIRED_GPU_MIN_DriverVersion)
```

- all jobs request singularity image

```
+SingularityImage = "/cvmfs/singularity.opensciencegrid.org/opensciencegrid/osgvo-el8:latest"
```

- unified parameter file for environment and imaging configuration
- all jobs use lightweight and specialized LibRA applications

Other highlights of the current implementation

GPU software execution:

- monitor GPU utilization

```
nvidia-smi --query-gpu=timestamp,name,utilization.memory,memory.used --format=csv -l 5 --id=${NVIDIA_VISIBLE_DEVICES} > working/logs/nvidia.${{jobmode}}.${{partId}}.out &
```

- copy system's libcuda.so.1 into application bundle

```
bundles_dir=`ls libra/bundles`  
echo "bundles_dir: $bundles_dir"  
if [ -e /.singularity.d/libs/libcuda.so.1 ]  
then  
    cp -f /.singularity.d/libs/libcuda.so.1 libra/bundles/${bundles_dir}/lib64  
else  
    if [ -e /lib64/libcuda.so.1 ]  
    then  
        cp -f /lib64/libcuda.so.1 libra/bundles/${bundles_dir}/lib64  
    else  
        echo "libcuda.so.1: File not found on known paths. Trying with packaged version"  
    fi  
fi
```

Future work / challenges

- Improve automation / reduce need of human intervention in running workflows:
 - Error: “Job credentials are not available” - fix deployed?
 - Applications and convolution functions currently pre-staged manually - is it a good use case for a Pelican origin?
 - Improve flexibility and scalability of data partition jobs
 - Deploy / integrate LibRA container