Evaluating Tape Storage at MIT





Motivation for study of a tape robot at MIT

- CMS write O(100 PB) of data per year that need to be stored on tape
- HL-LHC (~2030) will require an order of magnitude increase (Exa Bytes ?)
- Limited number of tape storage sites in CMS, only one in U.S.
- Vulnerability to tape site failures is significant: we had natural catastrophes (like fire, typhoon, and massive rain falls) and other circumstances affect various tape sites
- Opportunity at MIT arose to make use of the Harvard managed tape robot
- Unexplored aspect in CMS: use tape robot that is externally managed without direct access

University of Amherst (ATLAS) bought into the same Harvard tape robot.

Tomorrow at the joint ATLAS-CMS section we will present our different approaches with more technical details.

Any Tier2 functionality

- cores to run user jobs
- storage to store data
- data transfer mechanism

Tier1 = Tier2 + Tape Robot

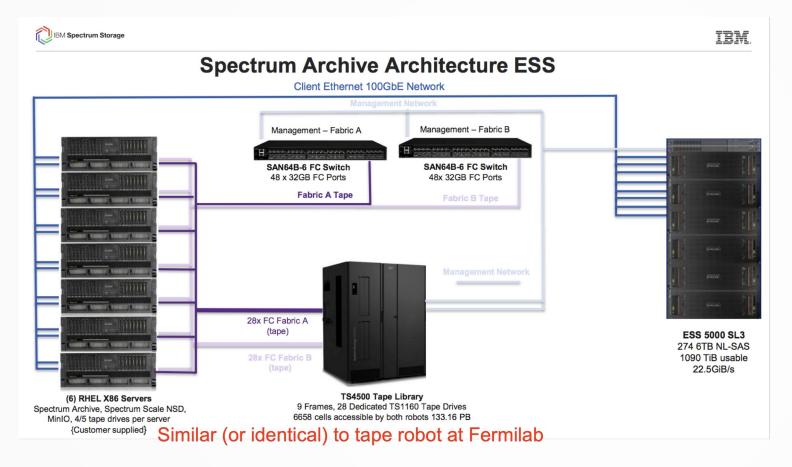
CMS experiment computing structure

- 8 Tier1 sites, one in US at Fermilab
- ~50 Tier2 sites, eight are in US
- our Tier2 site 25K cores, 23 PB of storage

	Tape capacity
T0_CH_CERN	320 PB
T1_US_FNAL	240 PB
T1_DE_KIT	45 PB
T1_UK_RAL	30 PB
T1_FR_CCIN2P3	47 PB
T1_ES_PIC	17 PB
T1_RU_JINR	25 PB
T1_IT_CNAF	63 PB

Harvard University bought and started to operate a tape robot

Harvard offers other groups to buy into tape (purchase tape cartridges)



Maximum Capacity: 157 PB 9 Frames, expandable to 18 34 TS1160 Tape Drives, max 11.2 Gb ESS-5000: 1.1 PB useable 100 Gb network IBM GPFS POSIX interface IBM Spectrum Archive Library Software Xrootd with staging Globus 5 with staging S3 via MinIO

As US CMS Tier2 site we have acquired

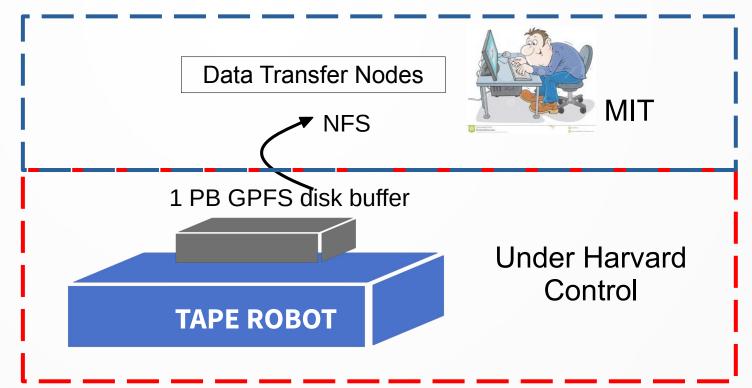
- ~16 PB of disk storage; accumulated over decade of buying disks
- bought 15 PB of tape storage for 1/10 of disk cost
 - + resilient storage, cheap
 - operational costs, reading is slow

Can we use it for CMS needs?

- as users we do not have access to tape libraries
- restrictive access to file system (security concerns)
- all other CMS tape sites own the robot and do not have any of those restrictions
- Tier1 tape interface with CMS assumes access to tape libraries

GPFS disk buffer is exposed to us though NFS And that means

- No access to tape libraries
 - → is file available on disk buffer, is it on tape?
 - → how do you stage out from tape onto disk?
- No capability for file extended attributes
 - → was transfer ok (checksum) ?



TAPE REST API Calls: there are two types of them

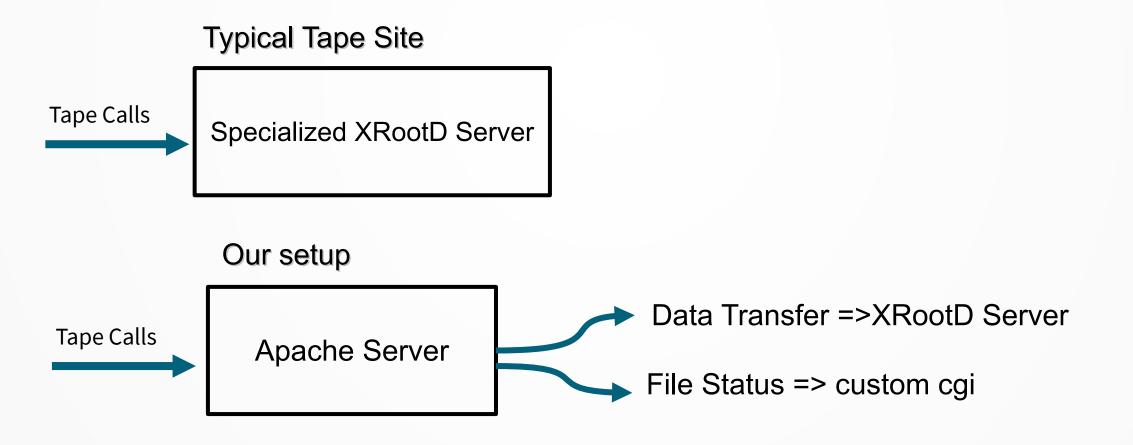
- File status calls
 - → is file available for immediate read (is it on disk)?
 - → stage it from tape onto disk
 - → has this file been written to tape?
- Data transfer calls (XRootD or GridFTP)
 - → do you have this file?
 - → what is checksum ?
 - → read a file
 - → write a file

In CMS all above calls are handled by tape sites utilizing specialized XRootD protocol (dCache). Underneath it assumes full access to the tape robot.

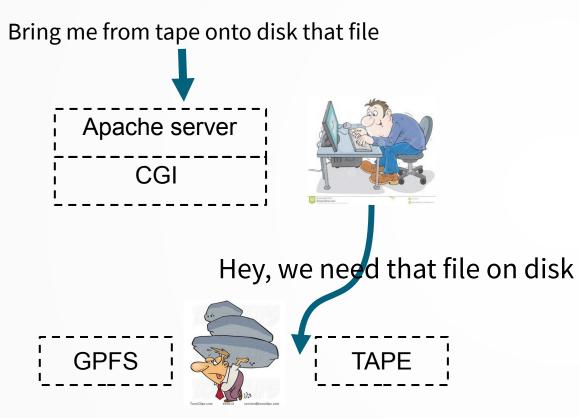
Our Solution: all calls are handled by an apache server

- data transfer calls are forwarded to XRootD servers
- all file status calls are handled by custom cgi (python) scripts

Same setup would apply to Globus GridFTP as a transfer protocol.



For example: stage out from tape call

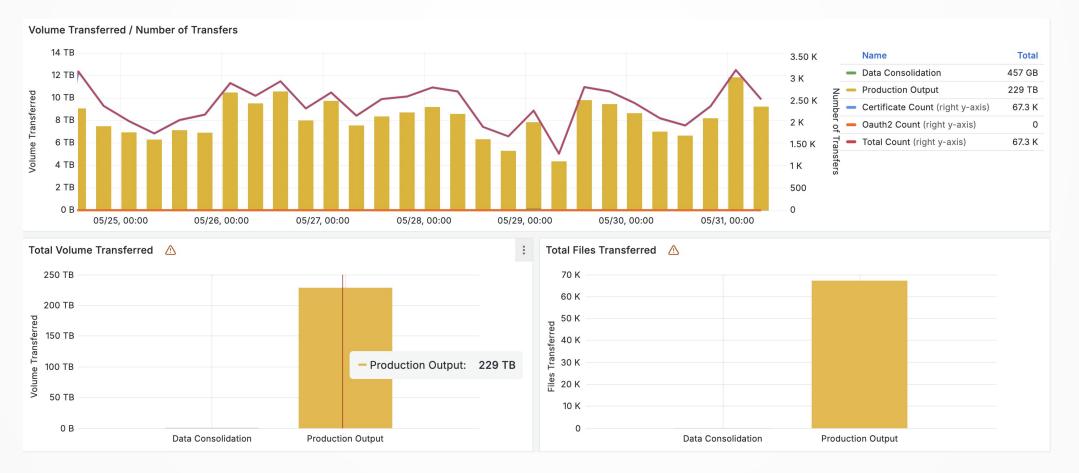


Harvard team does heavy lifting File becomes available for reading Data flow never stops. This is a typical week.

The amount of data on tape right now – 6.1 PB

Data writing is limited by network available: ~7 Gb

University promised to have 100 Gb available by the end of the summer



Tape reading is not as common at the moment. Will scale tape staging out in the future.

